Mansoura University

Faculty of Engineering

Prod. Eng. & Mech. Design Dept.



Theory of Machines

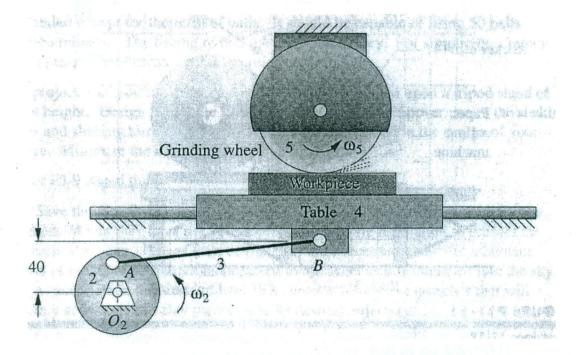
Final-Exam Fall 2012

Time: 3 hours

(Open Book Exam)

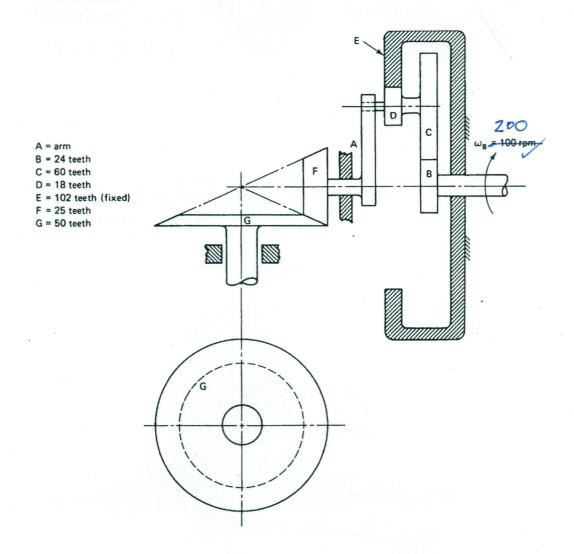
Please attempt the following questions:

1. The figure below shows a surface grinder table drive. The crank radius is 22 mm, the coupler is 157 mm, and the offset is 40 mm. The mass of table and workpiece combined is 50 kg. Find the driving torque of the crank necessary to overcome the inertia of sliding parts at crank angle equals 90° measured from the horizontal line. The acceleration of the slider at that position is 0.5 m/s² to the left. Find also the magnitude of the force at the crank pivot, O₂.



2. Determine a suitable base circle radius and the equations of the cam profile assuming that the translating flat-faced follower starts from a dwell from θ^o to 160^o . The rise occurs with cycloidal motion during the cam rotation from 160^o to 270^o . The fall then occurs with cycloidal motion for the cam rotation from 270^o to 360^o . The amplitude of the follower translation is 10 cm. The cam rotates in the clockwise direction.

3. The sun gear B of the figure shown below rotates at 200 rpm CW as viewed from the right. Determine the angular velocity and direction of ω_G as viewed from bottom.



- 4. A certain machine requires a torque of $(1410+200 \sin \theta)$ lb-ft to drive it, where θ is the angle of rotation of the shaft measured from some datum. The machine is directly coupled to an engine which produces a torque of $(1410+250 \sin \theta)$ lb-ft. The flywheel and other rotating parts attached to the shaft weigh 750 lb with radius of gyration of 18 in. The mean speed is 70 rpm. Determine:
 - a) The power of the engine.
 - b) The percentage fluctuation of the speed.
 - c) The maximum angular acceleration of the flywheel.

5. The rotor shown below has unbalanced weights $w_1 = 0.13 lb$, $w_2 = 0.2 lb$, and $w_3 = 0.13 lb$, at radial positions $r_1 = 4 in$, $r_2 = 3 in$, and $r_3 = 2 in$. Determine the necessary counterweight correction amounts and locations in balance planes at locations P and Q for complete static and dynamic balance of the rotor.

