Mansoura University.
Faculty of Engineering.
Electrical Engineering Dept.



Second Semester. Date: 8 -6-2013.

Time: Three Hrs for Two Parts.

Full Mark: (55)

Exam of (Power and Electrical Machines)
For 3rd Grad Mechanical Engineering Dept. students.

Answer All Questions.

Part (I)

First Question: (5+5+10 Marks)

- a) With the help of neat diagrams, **describe** the starting methods adopted for:
 - i- Three-phase squirrel-cage induction motor. ii- Three-phase slip-ring induction motor.
- b) With the help of neat diagrams, **classify** the single-phase motors according to their starting method, and **mention** their applications?
- c) A 440-V, 3-phase, 4-pole, 50-Hz, 37.3 kW, Y-connected induction motor has the following parameters:

 $R_1 = 0.1 \Omega$, $X_1 = 0.4 \Omega$, $R_2' = 0.15 \Omega$, $X_2' = 0.44 \Omega$

Motor has stator core loss of 1250 W and rotational loss of 1000 W. When motor operates at a slip of 3%, <u>using simplified equivalent circuit</u> calculate (i) input line current and p.f. (ii) electromagnetic torque developed in N-m (iii) output shaft power and (iv) efficiency of the motor.

Second Question: (8+12 Marks)

- a) For a three-phase synchronous generator connected to the bas bar explain the following
 - i) Synchronism conditions:
 - ii) Advantages of parallel operation.
 - iii) Effect of prime-mover speed change.
 - iv) Effect of field current change.
- b) A 10 MVA, 6.6 kV, 3-phase, Y-connected alternator has provided O.C.C. and S.C.C. test tables as under:

Field Current [A]	25	50	75	100	125	150	175	200	225
Line E.M.F. [kV]	2.4	4.8	6.1	7.1	7.6	7.9	8.15	8.35	8.5
S.C.C [A]			875						

The dc resistance measured between the two terminals is 0.173. Calculate the voltage regulation by: (i) Synchronous impedance method, (ii) Ampere-turns method at

- a) 90% of full-load and 0.8 lagging p.f;
- b) Full-load and unity p.f. (Comment about the results)

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aird Question: (15 Marks)

Choose the correct Answer:

- (1) A single phase induction motor employs.....rotor.
 - i) Squirrel cage
- ii) Wound
- iii) Either squirrel cage and wound
- iv) None of all
- (2) For the same rating, the size of a single phase induction motor is about.....
 - i) That of a 3-phase induction motor
 - ii) Three times 3-phase induction motor
 - iii) 1.5 times 3-phase induction motor
 - iv) 0.33 times 3-phase induction motor
- (3) For the same rating, the power factor of a single-phase induction motor is that of 3-phase induction motor.
 - i) The same as
- ii) less than
- iii) More than
- iv) none of all
- (4) The purpose of starting winding in a single phase induction motor is to.....

 - i) Reduce losses ii) Limit temperature rise
 - iii) Produce rotating flux in conjunction with main windings
 - iv) None of all
- (5) A capacitor-start, capacitor-run motor has.....
 - i) Low power factor
- ii) High power factor

 - iii) Low efficiency iv) Low starting torque
- (6) The nameplate of a single-phase, 4-pole, induction motor gives the following data: Output 373 W, 230 V, 50 Hz, input current 2.9 A, power factor 0.71, and speed 1410 r.p.m. the full-load slip of the motor is:
 - i) 6%
- ii) 2%
- iii) 4%
- iv) 3%
- (7) In the above question, what will be the efficiency of the motor:
 - i) 65.3%
- ii) 78.7%
- iii) 89.2%
- iv) 70.6%
- (8) The maximum voltage is induced in the rotor of a 3-phase induction motor when it.....

- i) Runs at no-load
- ii) Runs at full-load
- iii) Is blocked
- iv) None of all
- (9) The reactance of the rotor circuit of a 3phase induction motor is maximum.....
 - i) At no-load
- ii) At full load
- iii) At half full-load
- iv) None of all
- (10) If the slip of a 3-phase induction motor increases, the power factor of the rotor circuit...
 - i) Is increased
- ii) Is decreased
- iii) Remains unchanged iv) None of all
- (11) The maximum torque of a 3-phase induction motor under running conditions
 - i) Inversely proportional to supply voltage
 - ii) Inversely proportional to rotor reactance at stand still
 - iii) Directly proportional to rotor resistance
 - iv) None of all
- (12) In a synchronous machine, if ϕ is the flux per pole and f is the frequency of the emf induced E, then

 - i) $E \propto (\phi f)$ ii) $E \propto (\frac{1}{\phi} f)$
 - iii) $E \propto (\frac{\phi}{f})$ iv) $E \propto (\frac{f}{\phi})$
- (13) The voltage regulation of alternator delivering only resistive load is:
 - i) zero
- ii) low-positive
- iii) high-positive
- iv) negative
- (14) The voltage regulation of alternator delivering only inductive load is:
 - i) zero
- ii) low-positive
- iii) high-positive
- iv) negative
- (15) Short pitch winding results in
 - i) Higher terminal voltage
 - ii) Higher efficiency
 - iii) High power factor
 - iv) Better voltage wave form