Implementation of Transformer Static Differential Relay with Harmonic Blocking

مرحل تفاضلي ساكن ذو إعاقة فصل توافقية لوقاية محولات القوى

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ملخص - تقدم هذه الورقة مرحل تفاضلي ساكن يستخدم مرشحات الحزمة النشطة من الدرجة الثانية لتحديد نسبة التوافقية الثانية بما يمكن المرحل من عدم إصدار إثمارة الفصل خلال تيار الإندفاع المغناطيسي لمحولات القوى. و يتميز المرحل المنفذ بإمكانية إستخدامه مع العديد من مقننات محولات القوى بتعديل منحنيات الخواص التفاضلية.

Abstract – In this paper a transformer static/electronic differential relay is implemented using second order active band-pass filters for detecting second harmonic ratio. Thus enabling a relay-blocking signal during transformer inrush current, also the relay allows for a fine adjustment of the differential characteristic curve to facilitate its use in variety of transformer ratings.

I. INTRODUCTION

of One of the most important means transformer protecting power is differential protection based the comparison of the transformer primary and When these currents secondary currents. deviate from a predefined relationship, an internal fault is assumed and the de-energized. transformer is However during transient primary magnetizing inrush conditions, the transformer can carry very high primary current and no secondary current. The resulting differential current can falsely trip the transformer. The most common technique used for preventing false tripping during the above condition is the use of second harmonic restraint. If the second harmonic content of the differential current exceeds a pre-defined percentage of the fundamental, inrush is indicated and the relay is prevented from tripping.

Nikola R. and Adam S. [1], presented a method for the simulation of the inrush

phenomenon in which they considered the phenomenon as a quasi steady state as its slow attenuation makes time domain simulation difficult. C. E. Lin et al [2], related the transformer magnetizing inrush non-linearity phenomenon to the hysterisis of the iron core, as it results in analytical complexity. They further presented a symmetrical discussion [3] for due harmonic analysis to magnetizing inrush currents single-phase power jn transformers using the Fast Fourtier Transform (FFT). H .S. Bronzeado et al [4], stated that sympathetic inrush - which is the effect of transformer inrush current on other transformers already connected system - has been largely ignored. They reasoned the transient inrush occurring in transformers to the transformer core saturation caused by switching on. Laszlo Priler et al [5], mentioned two causes of magnetizing inrush; the residual flux in the magnetic core and the transient flux produced by the integral of the sinusoidal supply voltage. When energizing a transformer at zero crossing of the sinusoidal voltage, the prospective magnetizing current and the flux have their maximal values and delayed by 90 electrical degrees.

II. Static Relays In Protection

Static relays technology is a preeminent choice of protection. The application of these relays is in many ways simpler than that of EM relays, although there has no significant change in the principles of system protection and coordination.

David S. Baker et al [6] developed a static over-current and clarified relay coordination time intervals are adjusted, and how reset characteristics and setting of accuracy are implemented. Bruce, Baily and Dan Jakominich [7] developed a staticdigital over-current relay stating that digital technology has functionality that permits improved expanded protection. and B.T.Desai, Gupta and Vasantha implemented an inrush activated blocking scheme for a static electronic differential relay based on an instantaneous level of differential current and its rate of change. This scheme is based on the waveform approach. They mentioned that the current magnitude and rate of change of current (di/dt) are low simultaneously for inrush for about 40-45 degrees from zero crossing of the positive rise of the rectified current wave, compared to normal fault current and load current.

In this paper a more developed scheme of an electronic differential relay is implemented. The relay avoids the dependence on the current waveform pattern in which case it is not always guaranteed that the current waveform will maintain certain specifications under various loading or even inrush conditions.

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The present relay allows for second harmonic ratio detection using active bandpass filters by which mal-operation due to inrush condition is avoided. Furthermore, it is possible to adjust the slope of the characteristic curve electronically. The schematic and realization of the relay is depicted below.

III. Signal Conditioning

The primary and secondary currents of the power transformer are passed through current transformers then transformed to voltage signals by the 0.2Ω precision resistor as shown in figure (1). The primary and secondary signals are passed through two inverting amplifiers such that the gain of the secondary signal is one half that of the primary one.

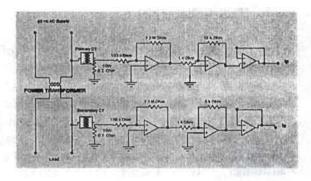


Fig. (1) Signal conditioning circuit.

To create signals corresponding to the primary and secondary currents for use in calculating differential and restraining currents of the characteristic curve, both signals are passed through active rectifiers as shown in figure (2) to create de levels corresponding to the primary and secondary currents.

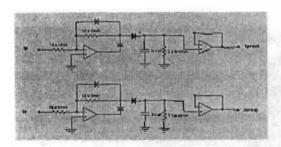


Fig. (2) Active rectifiers for primary and secondary signals.

IV. Characteristic Curve Implementation

The relay's characteristics are defined according to the following set of equations:

$$I_{diff} = (I_p - I_s)$$

$$I_{rest} = (I_p + I_s)/2 \rightarrow 1$$

$$I_{diff} > k * I_{rest}$$

The dc levels corresponding to the primary and secondary currents are modified as shown in figure (3) to give an output relevant to the restraining and differential currents using differential and adding amplifiers. A precision potentiometer resistor is used to adjust the required percentage (K).

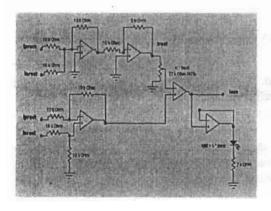


Fig. (3) Electronic implementation of characteristic curve.

V. Detection of second harmonic ratio

The ac primary signal corresponding to the primary current is passed through a second order active band pass filter tuned to give high gain for the 100 Hz signal as shown in figure (4), to detect the second harmonic. The signal is also passed through another active band pass filter tuned to give high gain for the 50 Hz signal to detect the fundamental frequency.

To calculate the second harmonic constraint percentage (ϵ), the 50 Hz filter output is passed through a precision variable resistor by which we can select any percentage (ϵ) from the 50 Hz signal (e.g. 0.12) to be compared to the 2nd harmonic signal.

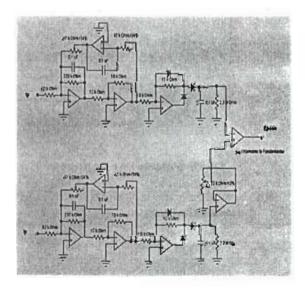


Fig. (4) Electronic detection of 2nd harmonic ratio.

VI. Tripping Circuit Logic

Finally our target is to send the tripping signal when the point of the characteristic curve is located in the operating zone in which $I_{diff} > I_{rest}$ AND the value of the

second harmonic ratio is less than "ɛ". As shown in figure (5), the signal "ɛ" is passed through the clock of a D-Q flip flop its Q' signal is connected to the cathode of a diode whose anode is connected to the signal corresponding to the logic of the characteristic curve via a resistor. As shown in the figure the transistor will not be triggered except when the point of the characteristic curve is in the operating zone AND Q' is high ("ɛ" is low) i.e. the 2nd harmonic ratio is less than 0.12.

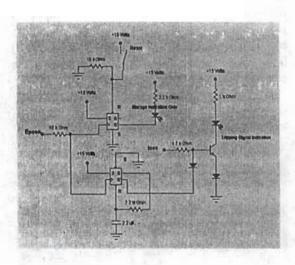


Fig. (5) Tripping circuit logic.

VII. Experimental Results

A digital storage oscilloscope was applied to measure the primary and secondary currents of the transformer during various operating conditions. The figures were captured using a digital camera. The inrush current signal captured by the relay in noload condition is shown in figure (6). A light emitting diode is used to indicate this condition.

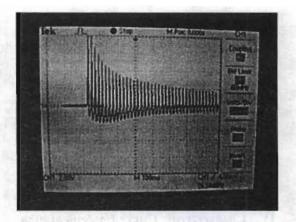


Fig. (6) Inrush current in no-load.

The inrush current signal in load condition is captured in figure (7) in which case also the 2nd harmonic LED remains on.

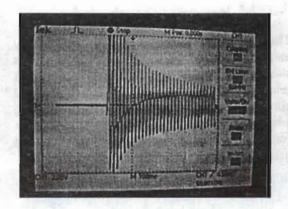


Fig. (7) Inrush current during load.

The primary and secondary current captured signals in normal and internal fault conditions are shown in figures (8) and (9) respectively. During the normal operation all LEDs are not activated, while during the internal fault condition the differential current LED and the tripping LED is activated.

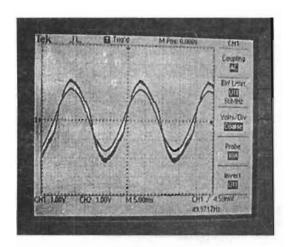


Fig. (8) Primary and secondary currents in normal operation.

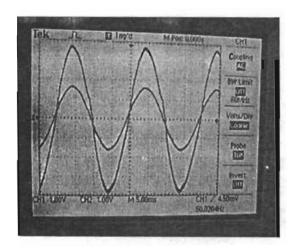


Fig. (9) Primary and secondary currents during internal fault.

VIII. Conclusion

A developed static differential relay is implemented and tested under various operating conditions. The relay allows for using harmonic blocking second active band-pass filters. Furthermore the shape of characteristic curve is adjustable, making it applicable to the protection of transformers with different ratings.

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